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## **Impact of Modern Ways of Farming on Agricultural Production: A Review**

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### **Abstract:**

The study of innovation has a long standing tradition in the field of agricultural economics. Particularly, the determinants of the adoption and diffusion of innovations go back a long while. In his seminal study on the adoption of hybrid corn in Iowa, Griliches (1957) developed an economic version of the S-shaped diffusion curve and confirmed that profitability gains positively affect adoption. Federet *al.* (1985) review a large body of empirical studies that originated in the work of Griliches. In a recent paper, Sundung and Zilberman (2000) provide the most comprehensive overview of this literature to date. Studying the determinants of innovation usually involves studying its impact, since innovation only occurs when the impact for the farmer is positive. However, in recent years, studies focusing solely on the impact of innovations have emerged. The aim of this paper is to discuss the impact of new technologies using two case studies of agricultural innovation, agricultural biotechnology and automatic milking. As this paper draws from two different research projects, not only the focus is different, also the methodology is.

### **Introduction:**

Agricultural research is conducted in the context of other economic and agricultural policies, but research is only one instrument of social policy, and most non-efficiency-related objectives are more effectively pursued using other policy instruments. Thus public-sector research should be treated as one of several available instruments for attaining agricultural sector goals, and decisions on research resources should reflect the reasons behind public sector involvement in research. In many places, stated objectives for the agricultural research system include (1) economic growth, (2) income distribution, and (3) food security. Environmental objectives are frequently voiced as well but can be thought of as falling under growth, distributional, and security objectives. For example, environmental concerns often arise when measures of growth fail to include the external costs associated with environmental damage or when the distribution of benefits to future generations may be jeopardized (Alston, Norton, and Pardey, 1995).

### **Agricultural Biotechnology in Arable Farming Distributional Issues:**

A central question in stimulating agricultural biotechnology research is the distribution of the benefits from this technology among all actors in the technology diffusion chain: input suppliers, farmers, processors, consumers, and government. Who gains and who (potentially) loses from these innovations? A popular argument used by the opponents of agricultural biotechnology is the idea of an input industry extracting all benefits generated by these innovations. Are life science firms able to appropriate all benefits or is there a limit to their monopoly power? The impact estimates can come from five sources, ranked according to increasing representativeness and reliability: (1) laboratory trials, (2) field trials, (3) on-farm



partial adoption trials, (4) on-farm field-level surveys, and (5) whole-farm surveys. The range of the estimates for Bt cotton, herbicide tolerant (HT) cotton, and HT soybeans, provided by Lin, Price, and Fernandez-Cornejo (2001). The estimates vary strongly according to the region, the dataset, and the methodology. In general, the distribution of the estimates tends to be skewed toward a positive yield increase and a negative pest control cost increase, especially for Bt cotton. For HT soybeans, some studies advance the evidence of a yield drag (Benbrook, 1999). However, the measured yield difference can be biased by the choice of varieties to be compared. In the case of a currently used conventional variety, which is compared to a transgenic variety, the latter is often penalised by the fact that it is not necessarily as well adapted to the biophysical and climatic conditions of the area as is the case with the conventional variety. Varieties are agro climatically specific, and thus varieties initially released by seed companies may not have been appropriate for all regions, especially the lower adopting regions (Falck-Zepeda, Traxler, and Nelson, 2000b). This will undoubtedly change as traits are genetically inserted in a larger set of varieties. A more accurate method is to compare yields in properly conducted side-by-side trials carried out with near-isogenic lines that differ only in the possession of the inserted gene. Such trials are the most reliable way to isolate the consequences of genetic differences, all other things being equal (Benbrook, 1999). Again, the near-isogenic conventional parent of the transgenic variety has generally not been among the set of conventional varieties farmers have chosen to grow in the area. So, although these trials give a direct measure of the genetic yield potential (the change in yield owing to the transgene only), they may result in an over-estimation of the farm-level impact of adopting the transgenic variety.

#### **Environmental and Human Health Externalities:**

There are many types of external effects in agriculture. An externality arises when there is a spillover effect of one person's actions on another person's economic opportunities and where that effect is not fully compensated through a market transaction (Alston, Norton, and Pardey, 1995). Many people are concerned that the capacity of agricultural systems (globally or locally) is being depreciated too rapidly by excessive exploitation of the natural resource base. Underlying this concern is an implicit belief that agricultural decision makers are discounting the future too heavily, that they find it optimal to consume the natural resource base too quickly, compared with some standard. Two possible rationales are that (1) private discount rates are greater than social discount rates and (2) some individuals attach too little weight to the welfare of future generations. Thus, the costs of environmental externalities, perceived by society, are inseparably linked to the definition of a discount rate, which is representative for the society as a whole. The lower (higher) the discount rate, the more society attaches weight to the welfare of future (present) generations. The decision-making rule for GMO's can be described as comparing – explicitly or implicitly – the expected costs of their release with the expected benefits. The release of the transgenic crop will be approved if the expected discounted sum of benefits exceeds the sum of the expected discounted costs. Traditional cost-benefit-analysis could result in socially nonoptimal allocation of resources because the value of delaying a decision and waiting for additional information is neglected. Generally, the decision can be seen as one under temporal uncertainty and irreversibility. Real



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option pricing theory has shown that under such circumstances, the benefits have to exceed the costs by a factor significantly greater than one to account for the option to delay the decision. This factor is commonly called the *hurdle rate* (Wesseler, 2000). In order to assess the total social costs of agricultural biotechnology

innovations, reliable data about the potential positive (declining pesticide use, declining toxicity of pesticides) and negative externalities (gene flow risks, loss of biodiversity) of these technologies are needed, as well as – and this part is often neglected – data about the externalities of conventional and alternative technologies. Conventional agricultural systems rely often on toxic pesticides, which leach into groundwater. Even systems based on mechanical weeding rely on heavy machines compacting soils, enhancing soil erosion, consuming fuel and emitting exhausts in the atmosphere. Since conventional agricultural techniques are already associated with some externalities, the correct evaluation of the total social costs and benefits of agricultural

biotechnology has to take them into account by computing the change in these costs when agriculture moves progressively from conventional to agricultural biotechnology techniques. If agricultural biotechnology applications in the EU are more environment-saving than conventional techniques, as they seem to promise, this would mean that the marginal social cost shift would be even greater than the rightward marginal private cost shift presented in and that net benefits (reduction of externality costs) are flowing to an important actor of the agricultural biotechnology diffusion chain: the environment. The major challenges in the coming years will be the (1) aggregation and (2) valorisation of the environmental benefits and costs associated with the introduction of genetically modified crops. Once an acceptable hurdle rate and social discount factor are defined, policy makers can make rational decisions on the regulatory approval of GM crops. However, much research still has to be done in the aggregation and valorisation of all potential private and social (environmental) benefits and costs involved in such decisions. The potential human health and environmental externalities of the two currently major GM traits, i.e. insect resistance and herbicide tolerance, are summarized via a case study on BT maize and HT soybeans (Nelson and De Pinto, 2001). Positive externalities appear in fat, while a regular font is used for the negative ones. A direct human health impact of biotechnology has been reported by Pray *et al.* (2000). The latter show that only 5 % of Chinese farmers in their sample report poisonings due to the application of insecticides on Bt cotton, while this figure is 22 % for the case of conventional non-transgenic cotton. Since this health impact is limited only to the farm operation, it is not an externality but a private (indirect or ‘non-pecuniary’) benefit of adopting transgenic Bt cotton. Crawley *et al.* (2001) monitor four different GM crops (HT oilseed rape, BT potato, HT maize and HT sugar beets) in 12 different habitats over a period of 10 years. The purpose is to find out if these crops would become weeds of agriculture or invasive of natural habitats, and that the introduced genes would be transferred by pollen to wild relatives. Gura (2001) reviews some environmental studies being undertaken in the UK, shedding light on some mixed effects of agricultural biotechnology. The purpose of the studies is comparing biodiversity (nontarget effects in Table 4:) in fields of HT beet, maize and oilseed rape with that in comparable plots of equivalent non-GM varieties. The central question is: “Will the



large-scale growing of these crops be damaging to wildlife?" A British researcher, for example, alarmingly observes that HT sugar beet and the associated application of glyphosate could almost eradicate the wild herb *Chenopodium album*, fat hen or lamb's quarters, and severely diminish skylark populations. On the other hand, the use of broad-spectrum herbicides in conjuncture with HT crops should mean that many fewer sprayings are needed. Fewer sprays should also slow the emergence of herbicide resistance in weed species. Moreover, the GM technology will allow farmers to avoid tilling the soil at the beginning of every season, a practice that is meant to destroy weeds, but which is also thought to diminish biodiversity by reducing soil moisture and nutrients, and increasing the risk of erosion. In contrast, Elmgaard and Pedersen (2001) observe that the implementation of HT fodder beets may increase biodiversity in beet fields. In general, the weed flora and arthropod fauna in HT plots contain more individuals and species than the conventional plots. They believe that this difference would benefit the avi-fauna during a period of time where food availability is critical to farmland birds. The use of Roundup as a weed-controlling agent is more powerful and efficient compared to conventional herbicide regimes in beet fields. When Roundup can be used in beet fields more weeds can be accepted for a period of time because control can be obtained in more developed weed vegetation. However, this improvement of conditions for flora and fauna relies on a delayed weed control. A dense and diverse weed flora is believed to benefit the fauna in several ways. Firstly, occurrence and density of the host affect herbivorous insect species thriving on specific weed species. Secondly, the microclimate and habitat structure of weedy spots attracts a number of arthropod species of different feeding guilds. Thirdly, the aggregation of arthropods for the aforementioned reasons may benefit predators including birds. The concern about potential development of resistance of insects (like e.g. European Corn Borer) against the toxins produced by Bt crops is justified. Therefore, industry and entomologists have focused attention on refuge management plans to combat resistance. Refuge zones are planted with the conventional non-GM varieties, allowing susceptible pests to mate with resistant pests slowing the proliferation of resistance. As part of the US Environmental Protection Agency's (EPA) conditional registration, a mandatory 20 % pesticide treated or 4 % untreated refuge is required for transgenic cotton. Different researchers have analysed refuge management plans in order to limit the development of resistance (Hurley, Babcock, and Hellmich, 1998, Babcock and Secchi, 1999, Hurley, Secchi, and Hellmich, 1999, Hyde *et al.*, 1999, Onstad and Guse, 1999, Secchi and Babcock, 1999, Mitchell, Hurley, and Hellmich, 2000, Livingstone, Carlson, and Fackler, 2000, Hyde *et al.*, 2000, Secchi and Babcock, 2001, Secchi *et al.*, 2001). These studies more or less agree that the EPA recommendations will be sufficient in order to prevent a catastrophic accelerated development of resistance. compounds of pesticides (Heimlich *et al.*, 2000), or some combination of these four elements.

### **The Triple Bottom of Automatic Milking**

#### **Changes in farm management:**

The milking robot has been introduced on a commercial farm for the first time in 1992. The milking robot is developed to make the physical assistance of the farmer during the milking of each cow unnecessary. This is however only the smallest change on the farm



(Kuipers and Van Scheppingen, 1992). For optimal benefit, a whole Automatic Milking System (AM-system) is built around the robot, not just as a replacement for a milking parlour, but as a management appliance. Hence, the AM-system differs from other agricultural technologies in that it not only takes over a process previously executed by men, but it implies a whole new way of managing a dairy farm. It not only changes the way the milking is carried out, but also the farmer's schedule, the feeding and the housing management. The AM-system integrates three management functions: milking frequency, individual concentrates allocation and cow traffic. The use of these three functions makes it possible to implement a planned regime in the milking robot dairy and to control it. Additional important functions of the system are the monitoring of milk quality, of cow and udder health and of cow fertility. A Management Information System (MIS), integrated in the system, analyses performance data for each cow and executes management decisions through expert systems. By incorporating milking frequency, concentrates allocation and cow traffic on an individual basis into the system's management functions, the full production potential of each cow can be utilised. This can result in a good utilisation and a high efficiency of the technological facilities (Deviret *et al.*, 1997). By using the data provided through the MIS for the observation of the cows, health and welfare problems may be detected earlier.

#### **Economic aspects:**

The costs of the above-mentioned factors are difficult to predict. Their contribution to the change in farm profits is determined by the specific situation on the farm and by the management capacities of the farmer. Especially the extent to which the farmer really exploits the positive effects that the AM-system can generate is important (Arendzen and Van Scheppingen, 2000). This will depend on the farmer's knowledge about and experience with the system. To be cost-effective, cows will need to be motivated to use the AM-system as many hours as possible (Parsons and Mottram, 2000). In general, the hypothesis is put forward that automatic milking increases fixed costs, but decreases variable costs.<sup>7</sup> However, considering the amount of factors playing a role, it is clear that there is a considerable variation possible in the effect of an AM-system introduction on profits for similar sized farms, and that it is very difficult to draw conclusions on the optimal number of milking boxes to use from herd size alone. Most studies about the profitability of the AM system expect that dairy farmers renovating a farm building or building a new stable are the main group for whom the decision for the introduction of the AM-system arises (Parsons and Mottram, 2000; Arendzen and Van Scheppingen, 2000; Dijkhuizen *et al.*, 1997; Kuipers and Van Scheppingen, 1992). They compare AM-adoption with the purchase of a traditional system, as they assume that the producer is at a point where the existing milking system needs replacing or requires modernisation. However, a survey among 32 German and Dutch robot users learned that only 22% of them needed a new stable at the time of the AM-system introduction (Decuyper in Landbouwen, 2000a). In addition, these studies always apply to a very specific set of assumptions and farm characteristics, such that it is difficult to generalise their results. According to Parsons and Mottram (2000), the robot is competitive with the conventional milking parlour for zero grazing systems, if the price of quota is low and assuming that the robot shows the same reliability as the conventional milking system.



They used a simulation model to test the costs and benefits of different management regimes for the AM-system. Another study, Dijkhuizen *et al.* (1997) estimated the break-even level of AM-system adoption on a 125-dairy cow farm in the Netherlands and the USA. The break-even level, defined as the equivalent level of investment to make the AM-system as profitable as a conventional milking parlour, was found to be nearly double that of the herringbone parlour system. A sensitivity analysis showed that the break-even level was particularly sensitive to changes in wage rates. The profitability of the automatic milking system can also be expressed in the *maximum acquisition value* (MAV), i.e. the amount of capital that may be invested in the system to achieve the same net farm result as with a traditional milking parlour. If the investment exceeds the MAV, net farm results will be smaller (Kuipers and Van Scheppingen, 1992). In that case, farmers who base adoption solely on the perception of how the new technology or equipment will increase the profitability of the dairy farm will not invest in the robot (Armstrong and Daugherty, 1997). Farmers looking for labour savings, more freedom, increased cow welfare etc. will only invest if they expect the lower profitability to be compensated by a desired fulfilment of their expectations. The MAV highly depends on the desired alternative for automatic milking. Capital which would normally be invested in renovation or replacement of a traditional milking parlour can be invested in an AM-system (Kuipers and Van Scheppingen, 1992). In practice, it can be expected that farmers considering buying an AM-system would also prefer a high degree of automation for the layout of a traditional milking parlour. The difference in investment with an AM-system will therefore be smaller. For farmers who would decide in favour of a cheaper and lower-tech alternative milking parlour, the step towards an AM-system is bigger. The AM-system will have the highest efficiency on farms with herd sizes that fit to the robot (Kuipers and Van Scheppingen, 1992) or, conversely, on farms where the farmer is willing, and able, to adjust the herd size to the AM-system. It is obvious that the milk yield per cow and the desired milking frequency are important factors in determining the number of cows that can be milked with an AM-system. The system's capacity (if expressed as number of cows per milking unit) also depends on whether the equipment is used efficiently (Devire *et al.*, 1997). In practice the milking frequency on commercial farms is 2.6 to 2.7 milkings per cow per day on average. The number of cows milked per hour mostly depends on the steady voluntary cow traffic throughout the day (Spahr and Maltz, 1997). According to the manufacturers, the capacity of a 1-box robot is 60 cows when the average daily milking frequency is assumed to be 2.8 to 3.0 milkings per cow. With a second box, they assert it to be 90 or 120 cows, depending on the system (differences are possible in the method of teat cleaning, system cleaning, teat cup attachment etc.) (Schoonhoven, 2000). Kingmans (1999) described how the available quorum influences the exploitation of the robot capacity as follows: "Having a quorum above approximately 450,000 litres, a 1-box system will be overloaded, while a second box will be under-utilised and thus used inefficiently. Farmers having a quorum that can be milked efficiently by a 1-box, but who want to expand the milking activity in the coming years, will also be confronted with a capacity problem. Only for a large growth, a second box becomes economically interesting".



It should be noted that in practice, there is a large variation in number of cows and litres of milk that are milked with a similar AM-system. Milk yield per cow and number of milkings per day are important determinants of the system's capacity. Furthermore, farmers can gain in capacity by selection of faster milking cows and by a more efficient use of the system when becoming more experienced. A dairy farmer may aim for a higher milk production per cow. The reason for this can be either to keep down the variable costs of the herd in the long term by milking the quota with a smaller number of cows, or to enlarge herd size and production per cow to profit from increasing scale. According to Bart Sonck (personal communication), most farmers do not have the intention to cut down their herd size because they see this as a step back. They usually think in terms of growth and enlargement. For example, a survey showed that only 20 % of the 32 interviewed robot milkers considered the higher production rates as an argument (Decuyper in Landbouweven, 2000a). The production increase with the AM system is reached through increased milking frequency and by combining individual milking and feeding strategies (Kuipers and Van Scheppingen, 1992; Deviret *et al.*, 1997). Kuipers and Van Scheppingen (1992) assumed a 10 to 15 % higher milk yield per cow to be possible. These values have been reached on experimental farms, but on commercial farms production increases are generally lower (with 5% as the estimated average) (Bart Sonck, personal communication). Moreover, the production increase has a fair amount of variance (Dijkhuizen *et al.*, 1997) and the advantage of a higher yield by increase of the milking frequency is gradually diminishing due to genetic progress (Landbouweven, 2000a). If a milk production increase occurs due to the AM-system use, quota can be milked with fewer cows. In that case, the European robotic milker has to choose between the purchase of additional milk quota and a reduction of herd size. If all the new milk produced requires a release of quota to cover it, an AM-system becomes much more unprofitable (Cooper and Parsons, 1999). According to Dijkhuizen *et al.* (1997) reducing herd size is economically the most interesting option when milk quota are at a high price level (e.g., 2.04 Euro in the Netherlands). As a consequence of the higher milking frequency or an enhanced freezing point caused by a slightly larger percentage of water in the milk or a combination of these two factors, a reduction in fat content (approximately 0.15%) may occur when milking automatically. There may also be an effect on protein content, but less apparent (a decline of 0.05% on average) (Dijkhuizen *et al.*, 1997). Lower fat and protein levels imply a slight decrease in the milk price for the farmer. Some farms have problems with milk quality after adoption, which can be due to an increase in the somatic cell count, a raised free fatty acid content or an increase in total bacterial count. It should however be stressed that the management of the farmer plays a determinant role in keeping up the milk quality level, in case of traditional as well as for automatic milking.

#### **Social aspects:**

Traditional farmers are generally risk-averse. They may seek security in using the same traditional methods their parents used and in avoiding borrowing money, even for investments. However, farmers may be interested in the milking robot, because of the attraction of something new and revolutionary. The AM-system may become a new kind of status symbol in dairy farming or it may be considered in the future as a necessity for



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a farmer's quality of life and pleasure at work. The conflict between looking for security and trying something new will influence the decision for or against adoption of the AM-system. In an interview with Hoefman (1998a), Van Scheppingen distinguished between three groups of dairy farmers:

1. farmers who choose for the robot despite an expected decrease in farm profits, because of their high appreciation of the expected labour reduction or the expected increase in flexibility, in milk production, in cow health, etc.;
2. farmers who only choose for the robot if they expect farm profitability to stay equal or to increase;
3. farmers who do not want to work with an AM-system because they prefer a strict daily planning and want to control the milking process themselves, or for other reasons.

Obviously, the introduction of an AM-system is not a good choice for every farmer. Its success largely depends on the specific farm situation (Kingmans, 1999). Particularly in the early days, farmers returned to the traditional way of milking after disappointing experiences with the AM-system. The reasons they gave were: disappointing labour reductions, problems with milk quality, the fact that one was not able to relax carrying a beeper that can give an alarm at any time of the day, disorders cows suffered from, high maintenance and electricity costs, high prices for quota reducing the possibility to increase capacity or difficulties to deal with the financial aspect (Hoefman, 1998b). The unfulfilled expectations or undesired implications may have been due to the 'child diseases' of the system or to the fact that information on the consequences of adoption was still scarce. A reason why a dairy farmer may be interested in robotic milking is the expectation of a reduction in labour. The change in labour time after adoption is however difficult to estimate.

It is very different from farm to farm and largely dependent on the chosen management functions, namely the system of cow traffic and the feeding system (from limited grazing to summer feeding) (Deviret *et al.*, 1997). Also the reliability of the technology, the level of use of the technology, the position of the AM-system in the stable, the herd size and the portion of the herd that cannot be milked automatically play a role. For example, Artmann and Bohlsen (2000) found that the labour time required on four farms with the AM-system ranged from 127% to 54% in comparison to conventional milking in herringbone parlours. Although this study was done on a very limited sample, it may give an indication of the largely varying results of labour time on AM-farms. Roovers (1999) stated that especially on one-person farms, the labour time gained for work outdoors or for other farm activities will be limited. According to Artmann and Bohlsen (2000), an AM-system with a fully-functioning facility and with consideration of a higher level of animal monitoring can create the possibility to save about two-thirds of the time needed in conventional milking practices. According to a study by Sonck (1995), the AM-system with human-controlled cow traffic applied during the whole year and with an average milking frequency of three times a day results in physical labour savings for milking of maximum 38% (or 470 hours/year). With computer-controlled cow traffic and cows kept indoor the whole year, a maximum reduction





of 66% (or 821.3hours/year) is reached. These percentages exclude time needed for repair or unexpected trouble shootings. Other studies mention potential labour savings of 300 up to 950 hours a year or as much as 2.6 hours a day for a herd size of 125 (Landbouweven, 2000b; Dijkhuizen *et al.*, 1997). It is generally accepted that the physical workload will decrease after adoption of an AM-system. Milking is classified in the category of light to moderately heavy labour (Belt, 1984). Health complaints a milker may have with back, neck and shoulders will be reduced by the introduction of an AM-system (Hildebrandt, 1989; Rossing *et al.*, 1997). The amount of repetitive monotonous tasks strongly diminishes. This can be the main reason for an older farmer with physical problems to choose for the AM-system, namely to be able to continue farming in an easier way.

The farmer's vision on labour organization is an important factor in the decision in favour or against an AM-system. Some farmers prefer to work in peak moments, whilst others prefer a lighter, but more continuous load (Bart Sonck, personal communication). When milking in the traditional way, a farmer is tied to fixed milking hours 7 days a week. Moreover, the traditional milking hours are considered to be socially unfavourable. With an AM-system, the farmer is relieved from the fixed daily milking times. The farmer has more freedom of time planning during the day, more flexibility and the opportunity to have a life-style more in line with that of people working in other sectors. This may make an important difference for the farmer's social life. On the other hand, a robot user must be available 24 hours a day to solve possible disturbances. Unpredictable interventions can be necessary when the system breaks down or when abnormal cow behaviour blocks the activities of the AM-system. These interventions will disturb the daily labour planning and even social activities of the farmer and his family. This may cause stress to the farmer, especially when work of a high priority has to be interrupted, and to the family life. The reliability of the AM-system will play an important role in this. The fact that one can get alarmed at any time of the day can be experienced as worse than the usual milking process (Sonck, 1995; Sonck, 1996). Some farmers only feel comfortable working with a strict planning: to milk in the morning and in the evening and to execute the other work in between the milking sessions (Hoefman, 1998a). In case of automatic milking, the contact with the cows is expected to be less intensive (Sonck, 1995). This idea can be one of the reasons not to buy a robot. Some farmers consider the contact with their animals of major importance for their pleasure at work and see it as the loss of a major element in their stockmanship to give away the milking task to a robot. With an AM-system, however, a good contact with and control of the cows remains very important for the health of the herd and consequently for a good technical result (Roovers, 1999). Only good care makes it possible to realise high productions in a justified way. A survey among Belgian robot milkers showed that most farmers did not feel to have less contact with their cows. On the contrary, thanks to the robot they had more time to observe their cows and to walk between their cows (MML, 2000). Furthermore, the robot farmer can do his routine checking at a moment of the day he chooses himself without having to milk at the same time. Physical environmental elements such as light, noise and climate are rather unfavorable in a conventional milking parlour. As the AM-farmer will spend less time in this unfavorable environment, the system can contribute to the health of the farmer (Sonck,



1996). In addition, milking conventionally is not without any risks according to statistics on accidents. Positive effects can be expected with the AM-system as there will be less direct contact with animals: the incidence of labour unfitness caused by milking activities will be rare.

### **Conclusions:**

The aim of this paper is to discuss the impact of modern ways of farming on agricultural production. Agricultural production cannot be isolated from the institutional, socio-economic and political scene in which they are embedded. Both innovations are entirely coherent within the paradigm of the *second agricultural revolution of Modern Times*, since they consist in a refinement of the already existing techniques. The first studies show that both technologies offer potential pecuniary benefits to farmers via increasing yields, and savings in management costs and input use. Moreover, the innovations also introduce some non-pecuniary benefits in the farm operation due to their convenience in use and the increased flexibility in agricultural tasks they provide.

On the other hand, both technologies entail new aspects complicating any assessment of their associated benefits and costs. The increasing involvement of the private sector in plant breeding research implies that the traditional flow of public-funded research benefits from farmers to consumers does not hold any longer. Increased concentration in the seed market allows the latter to take part in the rent creation process during the diffusion of agricultural innovations. Moreover, agricultural biotechnology and automatic milking innovations cannot be studied without taking into account the influence they exert on the environment and animal welfare. Finally, both technologies have shown to be prone for consumer opposition. The observed divergence of attitudes of different stakeholders in the technology diffusion chain is maybe the result of a narrow view on technological innovations in the past. For a long time, agricultural technologies have been evaluated, solely based on its private benefit-cost ratio. Much emphasis was put on farm profitability and commodity price declines. In reality, the introduction of new technologies has impacts far beyond the farm or the consumer alone. Some stakeholders are already absorbing externalities of technologies. The negative effects or 'costs' of pesticides are currently 'paid' by the environment. This means that the market optimum of agricultural technological innovations does not include any guarantee for 'sustainability' yet, since we may be excessively exploiting our natural resource base. Therefore, we might want to reconsider the conventional 'private' welfare framework of agricultural innovations by including 'social values', like environment, society, consumer views, and animal welfare, transforming it into a 'social' welfare framework.

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